Arnav Bajaj

arnavbajaj9@gmail.com | arnav-bajaj.com | https://github.com/Jackhammer9

Skills

Programming Languages: Python, C++, C#, JavaScript, Matlab

CAD: Autodesk Inventor, Solid Works, Blender

Machine Learning: Tensorflow, PyTorch, Scikit-learn Computer Vision: OpenCV, Mediapipe, OptiTrack

Parallel Computing: CUDA, cuDNN

Robotics: ROS, RoboDK

Electronics: Altium, LTSpice, Arduino

Web Development: HTML, CSS, React, Django, Three.js

Game Development: Unity Engine, Pygame, Bosca Ceoil, Unreal, Aesprite

Tools: Git, GitHub, LaTeX

Projects

Gyroscope and FSR Controlled Car: Sperry

- **Objective**: Create a robot controlled by wearable sensors (FSR + gyroscope) on the user's hand.
- Engineered a four-wheeled vehicle with Bluetooth communication for responsive, low-latency control.

Drone Project: Nimbus

- Objective: Develop a custom drone, including both flight controller and external controller.
- Built and programmed the Arduino-based flight controller featuring a PID loop to maintain flight stability.

Computer Vision: Hand gesture detection based video game controller

- Objective: Implement gesture-recognition to replace traditional game controllers.
- Used OpenCV and Mediapipe to identify multiple hand gestures with 85% accuracy.
- Integrated gesture inputs into a Unity game prototype, increasing accessibility and immersion.

Open Source Python Library: RedDownloader

https://github.com/Jackhammer9/RedDownloader

- **Objective:** Develop an open source downloader made for the reddit that enables user to download all media types in pristine quality.
- Gained 85+ GitHub stars and currently averages 1,000 monthly downloads on PyPI.

Experience

Web Automation Freelancer – Freelancer at Upwork.com

January 2021 – May 2022

- Provided social media automation and solutions to multiple clients, reducing manual workload by up to 75%.
- Devised a safety algorithm for Twitter accounts that mitigated bot attacks and secured profiles with a detection rate of **94%**.

Extracurricular

Astra Robotics - Member

September 2022 – May 2023

- Was an integral member of the Astra Robotics Club, Collaborated on the HAL logistics robot project
- Revamped the club website using Three.js and ReactJS, improving load times and user experience.

Education

Technische Hochschule Würzburg-Schweinfurt – B.Eng in Robotics Engineering

Graduation: March 2027

• Developed a line follower robot, learnt camera calibration, simulink, soldering, machine vision algorithms and navigation algorithms through various Robotic Labs.